



**Weierstrass Institute for
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Maximum likelihood estimation for jump diffusions

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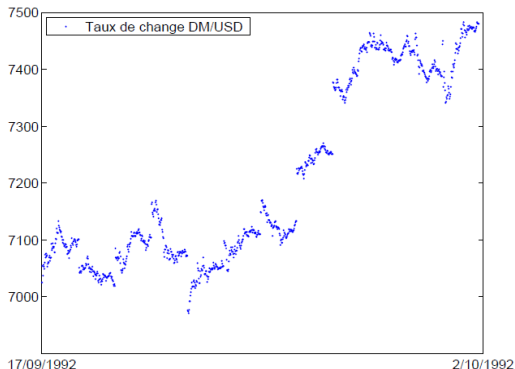


Figure 1: Jumps in the trajectory of DM/USD exchange rate, sampled at 5-minute intervals.

$$dX_t = \gamma(X_t, t) dt + \sigma(X_{t-}, t) dL_t, \quad t \in [0, T]$$

$$X_0 = x$$

Mathematical finance

- Option pricing: Merton [1976]
- Stochastic volatility models: Heston [1993], Barndorff-Nielsen and Shephard [2001]
- Interest rate models: Cox, Ingersoll and Ross [1985]

Condensed matter physics

Atomic diffusion modelling in Hall and Ross [1981]

Neuroscience

Neuronal membrane potential in Jahn, Berg, Hounsgaard and Ditlevsen [2011]

Consider an SDE with driver $(L_t, t \geq 0)$ on a filtered probability space $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \geq 0}, P)$

$$dX_t = \gamma(X_t, t, \theta) dt + \sigma(X_{t-}, t) dL_t, \quad t \in [0, T]$$

$$X_0 = x$$

L a Lévy process and parameter $\theta \in A \subset \mathbb{R}$. We call the solution X a **jump diffusion**.

Recall that L is a Lévy process if

- L has **independent and stationary increments**,
- L is **continuous in probability**, i.e. $p - \lim_{t \rightarrow s} L_t = L_s$

How to estimate θ efficiently when

- $(X_t)_{t \in [0, T]}$ observed continuously?
- given discrete observations X_{t_1}, \dots, X_{t_n} ?

Define

$$\begin{aligned}K_t(x, A) &= \int_{\mathbb{R}^d} \mathbf{1}_{A \setminus \{0\}}(\gamma(t, x)) \mu(dy), \\ \beta(\theta, s, x) &= \delta(\theta, s, x) + b + \int_{|x|>1} y K_s t(x, dy), \\ c(s, x) &= \gamma(t, x)\gamma(t, x)' \\ a(\theta, \theta', s, x) &= \beta(\theta, s, X) - \beta(\theta', s, x).\end{aligned}\tag{1}$$

Under suitable conditions on the coefficients of X the Hellinger process h for the absolute continuity problem induced by X is given by

$$h_t(\theta, \theta') = \int_0^t (c(s, X_t)^{-1} a(\theta, \theta', s, X_t))' c(s, X_t) (c(s, X_t)^{-1} a(\theta, \theta', s, X_t)).$$

Theorem

Suppose that the coefficients are locally Lipschitz and c is strictly positive definite. Then

(i) $P_t^\theta \stackrel{loc}{\ll} P_t^{\theta'}$ if and only if

$$P^\theta(h_t(\theta, \theta') < \infty) = P^{\theta'}(h_t(\theta, \theta') < \infty) = 1.$$

(ii) If (i) holds the likelihood function is given by

$$\frac{dP_t^\theta}{dP_t^{\theta'}} = \exp \left[\int_0^t c(s, X_{s-})^{-1} a(\theta, \theta', s, X_{s-}) dX_s^c - \frac{1}{2} \int_0^t a(\theta, \theta', s, X_s)' c(s, X_{s-})^{-1} a(\theta, \theta', s, X_s) ds \right]$$

here X^c denotes the continuous martingale part under $P^{\theta'}$.

Let $(L_t, t \geq 0)$ be a Lévy process on $(\Omega, \mathcal{F}, (\mathcal{F}_t), P)$. For every $a \in \mathbb{R}$

$$dX_t = -aX_t dt + dL_t, \quad t \in \mathbb{R}_+, \quad X_0 = x, \quad (2)$$

defines an Ornstein-Uhlenbeck process driven by the Lévy process L .

Equivalently,

$$X_t = e^{-at} X_0 + \int_0^t e^{-a(t-s)} dL_s. \quad (3)$$

The likelihood function is

$$\frac{dP_t^{a'}}{dP_t^a} = \frac{dP_0^{a'}}{dP_0^a} \exp \left(\int_0^t \frac{(a' - a)}{\sigma^2} X_{s-} dX_s^c - \frac{(a' - a)^2}{2\sigma^2} \int_0^t X_s^2 ds \right),$$

where X^c denotes the continuous martingale part of X under P^a .

The MLE for a is

$$\hat{a}_T = - \frac{\int_0^T X_{s-} dX_s^c}{\int_0^T X_s^2 ds}.$$

The form of the likelihood function means that we are in curved exponential family setting (cf. Küchler and Sørensen (1997)).

Theorem

- If $\sigma^2 > 0$ the MLE

$$\hat{a}_T = -\frac{\int_0^T X_s - dX_s^c}{\int_0^T X_s^2 ds}.$$

exists and is strongly consistent.

- If furthermore X is stationary and $E_\alpha[X_0^2] < \infty$ then under P^α

$$\sqrt{T}(\hat{a}_T - a) \rightarrow N\left(0, \frac{\sigma^2}{E_\alpha[X_0^2]}\right) \quad \text{weakly}$$

as $T \rightarrow \infty$.

Theorem

Assume that X is stationary and $E_a[X_0^2] < \infty$, then the following holds:

1. The statistical experiment $\{P^a, a \in \mathbb{R}\}$ is locally asymptotically normal.
2. The maximum likelihood estimator \hat{a}_T is asymptotically efficient in the sense of Hájek-Le Cam.

Let $(L_t, t \geq 0)$ be a Lévy process on $(\Omega, \mathcal{F}, (\mathcal{F}_t), P)$. For every $a \in \mathbb{R}$

$$dX_t = -aX_t dt + \sqrt{X_t} dL_t; \quad 0 \leq t \leq T$$

defines **Cox-Ingersoll-Ross process** X driven by the Lévy process L . No explicit solution is known for this SDE.

The likelihood function for continuous-time observations is

$$\frac{dP_T^a}{dP_T^0} = \exp \left[-\frac{1}{\sigma^2} (X_T^c - X_0^c) - \frac{a}{\sigma^2} \int_0^T X_t dt. \right]$$

where X^c denotes the continuous martingale part of X under P^a .

The MLE for a is

$$\hat{a}_T = -\frac{X_T^c - X_0^c}{\int_0^T X_t dt}. \quad (4)$$

Theorem

Let X be stationary, $\sigma^2 > 0$ and $E[X_0^2] < \infty$. Then the MLE \hat{a}_T is consistent and

$$\sqrt{T}(\hat{a}_T - a) \xrightarrow{\mathcal{D}} N(0, \sigma^2 E[|X_0|^{-1}]) \quad (5)$$

as $T \rightarrow \infty$.

Moreover, the model is locally asymptotically normal such that the MLE is efficient in the sense of Hájek-Le Cam.

Let L be a Lévy process with Lévy -Khintchine triplet (γ, σ^2, μ) and consider the following linear stochastic delay differential equation (SDDE) driven by L .

$$dX_t = aX_t dt + bX_{t-1} dt + dL_t, \quad t > 0 \quad (6)$$

$$X_t = X_t^0, \quad t \in [-1, 0], \quad (7)$$

where $a, b \in \mathbb{R}$ and $X^0 : [-1, 0] \times \Omega \rightarrow \mathbb{R}$ is the initial process with càdlàg trajectories that is assumed to be independent of L .

The likelihood function reads

$$L(\theta, X, T) = \frac{dP_T^\theta}{dP_T^{(0,0)}} = \exp\left(\theta' V_T - \frac{1}{2} \theta' I_T \theta\right),$$

where

$$V_T = \begin{pmatrix} \int_0^T X_t dX_t^c \\ \int_0^T X_{t-1} dX_t^c \end{pmatrix}$$

and I_T is the observed Fisher information

$$I_T = \begin{pmatrix} \int_0^T X_t^2 dt & \int_0^T X_t X_{t-1} dt \\ \int_0^T X_t X_{t-1} dt & \int_0^T X_{t-1}^2 dt \end{pmatrix}.$$

Theorem

Assume that X is a stationary solution, then the MLE $\hat{\theta}_T$ is strongly consistent, i.e. under P^a

$$\hat{\theta}_T \xrightarrow{a.s.} \theta \text{ as } t \rightarrow \infty.$$

Theorem

Assume that X is a stationary solution, then

$$T^{1/2} \left(\hat{\theta}_T - \theta \right) \xrightarrow{\mathcal{D}} N \left(0, \Sigma^{-1} \right)$$

where

$$\Sigma = \sigma^2 \begin{pmatrix} \int_0^\infty x_0(s)^2 ds & \int_0^\infty x_0(s)x_0(s+1) ds \\ \int_0^\infty x_0(s)x_0(s+1) ds & \int_0^\infty x_0(s)^2 ds \end{pmatrix}.$$

and x_0 denotes the fundamental solution.

By the Lévy-Itô decomposition of L we can write X as

$$X_t = X_0 - a \int_0^t X_s ds + \sigma W_t + J_t, \quad t \geq 0,$$

where W is a standard Wiener process and J a quadratic pure jump process in the sense of Protter given by

$$J_t = \int_{\{|x|<1\}} x(N_t(dx) - t\mu(dx)) + bt + \sum_{0 \leq s \leq t} \Delta X_s 1_{\{|\Delta X_s| \geq 1\}}.$$

Hence, the continuous martingale part of X under P^a is

$$X^c = W_t - a \int_0^t X_s ds.$$

An interesting question is the influence of jumps on the MLE. Define

$$X_t^j(\epsilon) = \int_{|x| \leq \epsilon} x(N_t(dx) - t\mu(dx)),$$

then the resulting estimate remains strongly consistent.

Theorem

Let us assume that X is stationary with $E[X_0^2] < \infty$, $\sigma^2 > 0$ and set

$X^{cj}(\epsilon) = X^c + X^j(\epsilon)$. If we define

$$\tilde{a}_T^\epsilon = - \frac{\int_0^T X_s - dX_s^{cj}(\epsilon)}{\int_0^T X_s^2 ds},$$

then $\tilde{a}_T^\epsilon \rightarrow a$ with probability 1 as $T \rightarrow \infty$.

Theorem

Let X be a stationary Ornstein-Uhlenbeck process with $E_a[X_0^2] < \infty$, then

$$\sqrt{T}(\tilde{a}_T^\epsilon - a) \rightarrow N(0, \Sigma(\epsilon)) \text{ as } T \rightarrow \infty$$

where

$$\Sigma(\epsilon) = E_a[X_0^2]^{-1} \sigma^2 + E_a[X_0^2]^{-1} \int_{|x| < \epsilon} x^2 \mu(dx).$$

The LSE for the parameter a is

$$a_T^{LS} = -\frac{\int_0^T X_s - dX_s}{\int_0^T X_s^2 ds}$$

From the theorem it follows for the asymptotic variances

$$AVAR_{LSE} - AVAR_{MLE} = E_a[X_0^2] \int_{\mathbb{R}} x^2 \mu(dx) > 0.$$

This motivates the jump filtering approach that will be discussed in the next section.

■ Observation scheme:

Observation points $0 = t_1 < \dots < t_n = T_n$ such that $T_n \xrightarrow{n \rightarrow \infty} \infty$ and

$$\Delta_n = \max\{|t_{i+1} - t_i|, 1 \leq i \leq n-1\} \xrightarrow{n \rightarrow \infty} 0.$$

■ Discretized MLE with jump filter:

$$\bar{a}_n := - \frac{\sum_{i=1}^n X_{t_i^n} \Delta_i X \mathbf{1}_{\{|\Delta_i X| \leq v_n\}}}{\sum_{i=1}^n X_{t_i^n}^2 \Delta_i^n}$$

for $\Delta_i X = X_{t_{i+1}} - X_{t_i}$ and some cut-off sequence $v_n > 0$.

Assumption

1. There exists $\alpha \in (0, 2)$ such that as $v \downarrow 0$

$$\int_{-v}^v x^2 \mu(dx) = O(v^{2-\alpha}). \quad (8)$$

2. There exists $\delta > 0$ such that for all $\epsilon \leq \delta$

$$E[\Delta_i M \mathbf{1}_{\{|\Delta_i M| \leq \epsilon\}}] = 0$$

Theorem

If Assumption 1. and 2. hold and $v_n = \Delta_n^\beta$ for $\beta \in (0, 1/2)$ such that $T_n \Delta_n^{1/2-\beta} = o(1)$ as $n \rightarrow \infty$ then

$$T_n^{1/2}(\bar{a}_n - a) \xrightarrow{\mathcal{D}} N(0, \sigma^2 E[X_0^2]^{-1}).$$

Furthermore, the estimator is asymptotically efficient.

Hence, the truncated MLE is **asymptotically efficient** in the sense of Hájek-Le Cam.

1. Choose the threshold v_n such that the continuous part is approximated in the limit.
2. Show that \bar{a}_n has the same asymptotic behavior as the following benchmark estimator

$$\hat{a}_n = -\frac{\sum_{i=1}^n X_{t_i^n} \Delta_i X(u_n)}{\sum_{i=1}^n X_{t_i^n}^2 \Delta_i^n}.$$

3. Prove a CLT for the benchmark \hat{a}_n .
4. Finally, show that the drift is negligible and

$$T_n^{1/2}(\bar{a}_n - \hat{a}_n) \xrightarrow{p} 0.$$

Define for $n \in \mathbb{N}$ and $i \in \{1, \dots, n\}$

$$A_n^i = \left\{ \omega \in \Omega : \mathbf{1}_{\{|\Delta_i X| \leq v_n\}} = \mathbf{1}_{\{\Delta_i N(B_{u_n}^c) = 0\}} \right\}$$

where $B_{u_n} = [-u_n, u_n]$, its complement $B_{u_n}^c$ and $N(B_{u_n})$ counts the jumps of L in B_{u_n} .

Lemma

Let $v_n, u_n \downarrow 0$ such that for the Lévy measure μ of L

- $\frac{\mu(B_{2v_n} \setminus B_{u_n})}{\mu(B_{u_n}^c)} = o(T_n^{-1})$ and
- $u_n^2 v_n^{-2} = o(T_n^{-1})$.

Then, it follows that for $A_n = \bigcap_{i=1}^n A_n^i$ we have

$$P(A_n) \rightarrow 1 \text{ as } n \rightarrow \infty.$$

To prove the CLT for \bar{a}_n we introduce a benchmark estimator

$$\hat{a}_n = -\frac{\sum_{i=1}^n X_{t_i} \Delta_i X(u_n)}{\sum_{i=1}^n X_{t_i}^2 \Delta_i^n}.$$

Lemma

Under the Assumptions of the previous lemma and if $\Delta_n^{1/2} \mu(B_{u_n}^c) = o(T_n^{-1})$ it follows that

$$\left| \sum_{i=0}^{n-1} X_{t_i} (\Delta_i X \mathbf{1}_{\{|\Delta_i X| \leq v_n\}} - \Delta_i X(u_n)) \right| = o_p(1)$$

as $n \rightarrow \infty$.

The following lemma leads to a CLT for the benchmark estimator.

Lemma

Let X be stationary with finite second moments. Set $\tilde{X}(u_n) = \sigma W + J(u_n)$ then

$$T_n^{-1/2} \sum_{i=0}^{n-1} X_{t_i^n} \Delta_i^n \tilde{X}(u_n) \xrightarrow{\mathcal{D}} N(0, \sigma^2 E_a[X_0^2]) \text{ as } n \rightarrow \infty.$$

- We have developed a maximum likelihood approach for drift estimation in jump diffusions.
- The jumps lead to an inefficient LSE in this class of processes.
- Several examples like Ornstein-Uhlenbeck, Cox-Ingersoll-Ross and linear stochastic delay equations lead to explicit MLEs.
- Strong optimality properties have been demonstrated for the MLE in these models.
- For the OU process the discretized MLE attains the efficiency bound from the continuous case when a jump filter is employed.
- The estimator can be computed directly and performs well for finite sample size.