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# Factorisable Sparse Tail Event Curves with Expectiles

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# Factorisable Sparse Tail Event Curves with Expectiles\*

Oberwolfach Report: New Developments in Functional and Highly  
Multivariate Statistical Methodology

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Data are observed more and more in form of curves, thus prompting a joint modelling to find out common patterns and also individual variations. Real data curve modelling occurs e.g. in neuroeconomics, wind speed analysis, demographics among many other disciplines.

Functional data analysis studies variation of random objects in a high dimensional context and provides insight into main factors, typically extracted as principal components via a Karhunen-Loève decomposition. However, in a variety of applications one is more interested in the tail behavior rather than the variations around the mean. Thus the analysis of curve variation is around a tail event curve (TEC) rather than around a mean curve as in functional PCA. TECs may be identified through tail probabilities or more general through functions based on conditional tail events. Modeling such Tail Event Curves (TEC) requires to deviate from Hubert  $\ell_2$  geometry and to introduce asymmetric norms or check functions. For example, quantile regression is a widely used method can be exploited to grasp the whole information on the conditional distribution and especially the tail structure, which plays crucial roles in risk management. Concerning multivariate

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quantile regression, many previous works study in this direction under different frameworks. But none of them worked in high-dimensional case. [2] introduced factorisable sparse tail event curves (FASTEC) method to implement high-dimensional multivariate quantile regression.

fMRI risk perception analysis requires to study the shape (e.g., amplitude, delay, and duration) of the estimated hemodynamic response function (HRF) to particular tasks answered by every individual. More noteworthy, extreme behaviors of the response function may reveal unobserved neuronal activation information. Therefore, we need a global measure which can capture the tail moments and be more sensitive to the outliers. Expectiles can be a better choice than quantiles in consideration of extremes although it is not robust. This fact motivates us to build an expectile based FASTEC model.

Denote  $\mathbf{Y} = (Y_{ij}) \in \mathbb{R}^{n \times m}$  as the multivariate curves we want to jointly model, where  $n$  is the length of observations and  $m$  is the number of curves.  $\{\mathbf{X}_i\}_{i=1}^n \in \mathbb{R}^p$  are the covariates with dimension  $p$ , e.g., B-spline basis. Both  $p$  and  $m$  are allowed to tend to infinity with the sample size  $n$  (but no quicker than  $n$ ).

Let  $e_j(\tau|\mathbf{X}_i)$  be the conditional expectile function of  $Y_{ij}$  given  $\mathbf{X}_i$ , for  $i = 1, \dots, n$  and  $j = 1, \dots, m$  with  $\tau \in (0, 1]$ , and approximate it by a linear factor model,

$$Y_{ij} = e_j(\tau|\mathbf{X}_i) + u_{ij}$$

$$e_j(\tau|\mathbf{X}_i) = \sum_{k=1}^r \psi_{j,k}(\tau) f_k^\tau(\mathbf{X}_i), \quad (1)$$

where  $f_k^\tau(\mathbf{X}_i)$  is the  $k$ th factor,  $r$  is the number of factors (much less than  $p$ ),  $\psi_{j,k}(\tau)$  are the factor loadings. Furthermore, factors are constructed by linear combination of covariates  $\mathbf{X}_i$

$$f_k^\tau(\mathbf{X}_i) = \mathbf{X}_i^\top \boldsymbol{\varphi}_k(\tau). \quad (2)$$

Substituting (2) into (1) yields

$$e_j(\tau|\mathbf{X}_i) = \mathbf{X}_i^\top \boldsymbol{\gamma}_j(\tau), \quad (3)$$

with  $\boldsymbol{\gamma}_j(\tau) = (\sum_{k=1}^r \psi_{j,k}(\tau) \boldsymbol{\varphi}_{k,1}(\tau), \dots, \sum_{k=1}^r \psi_{j,k}(\tau) \boldsymbol{\varphi}_{k,p}(\tau))^\top$  as the unknown coefficient vector. In multivariate case, what needs to be estimated becomes a  $p \times m$  coefficient matrix  $\boldsymbol{\Gamma}$ , where  $\boldsymbol{\gamma}_j(\tau)$  in (3) is the  $j$ th column of  $\boldsymbol{\Gamma}$ .

With increasing dimension of both explanatory and response variables one faces the difficulty of estimating a very high dimensional coefficient matrix. A natural way to reduce the burden of this estimation task is to introduce a penalty term. [4] proposed a penalization approach with nuclear norm, the sum of the singular values of the coefficient matrix as the penalty. Numerically the estimator can be easily obtained since it involves a convex optimization. Moreover, compare with previous traditional works such as reduced rank approach, the number of factors does not need to be predetermined. Dimension reduction and coefficient estimation can be done simultaneously.

To be more precise it is proposed to estimate the coefficient matrix  $\mathbf{\Gamma}$  by solving:

$$\widehat{\mathbf{\Gamma}}_{\lambda}(\tau) = \arg \min_{\mathbf{\Gamma} \in \mathbb{R}^{p \times m}} F(\mathbf{\Gamma}), \quad (4)$$

$$F(\mathbf{\Gamma}) = (mn)^{-1} \sum_{i=1}^n \sum_{j=1}^m \rho_{\tau}(Y_{ij} - \mathbf{X}_i^T \mathbf{\Gamma}_{\cdot j}) + \lambda \|\mathbf{\Gamma}\|_*, \quad (5)$$

$$\rho_{\tau}(u) = |\tau - \mathbf{1}\{u < 0\}| |u|^2. \quad (6)$$

Nuclear norm  $\|\mathbf{\Gamma}\|_*$  is defined by  $\sum_{l=1}^{\min(p,m)} \sigma_l(\mathbf{\Gamma})$  given the singular values of  $\mathbf{\Gamma}$ :  $\sigma_1(\mathbf{\Gamma}) \geq \sigma_2(\mathbf{\Gamma}) \geq \dots \geq \sigma_{\min(p,m)}(\mathbf{\Gamma})$ . The convexity of the nuclear norm results in a convex optimization problem that can be solved via various of efficient methods. The number of nonzero singular values of  $\mathbf{\Gamma}$  is identified as  $r$ . A high dimension  $p \times m$  is reduced to  $r \times \max(p, m)$  by regularization, when  $\mathbf{\Gamma}$  is sparse. After obtaining the  $\widehat{\mathbf{\Gamma}}_{\lambda}(\tau)$  from (4), singular value decomposition (SVD) can be employed to estimate the factors and normalized factor loadings respectively.

Moreover, the loss function for expectile regression has a smooth convex function form. Combining with the nuclear norm penalty, we can use Fast Iterative Shrinkage-Thresholding Algorithm proposed by [1] to solve the optimization directly. Without smoothing the asymmetric absolute check function, the convergence rate in the iterative procedure is quicker than in quantile regression case. Based on the unified framework for high-dimensional  $M$ -estimators with decomposable regularizers provided by [3], the finite sample oracle properties of the estimator associated expectile loss and nuclear norm regularizer are studied formally in this paper.

As an empirical illustration, our model is applied on fMRI data to see if individual's risk perception can be recovered by brain activities. Results show that main factors can reflect the common patterns of curves. Factor loadings over different tail levels can help to find out the most risk-seeking and averse behaviours. Taking tail risks into consideration, individual's risk attitudes can be predicted more precisely, especially the extremes.

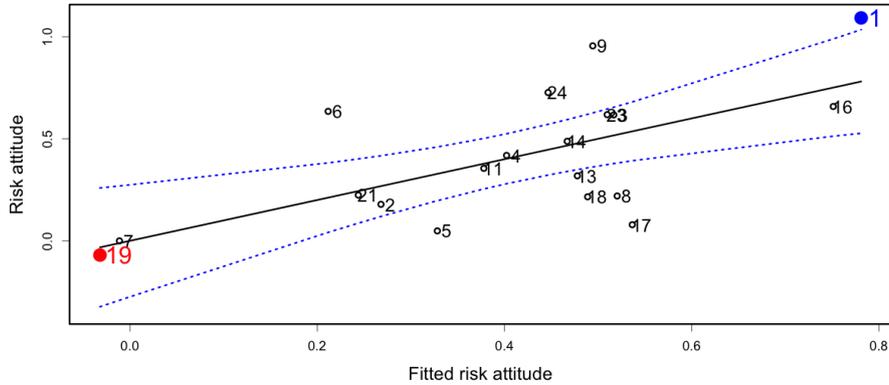


Figure 1: Horizontal axis denotes the fitted risk attitudes by the first factor loadings estimated from the brain data when  $\tau = 0.1$ , vertical axis denotes the risk attitudes parameters based on their choices. #1 and #19 are the most risk-averse and risk-seeking people respectively.

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